



# Programming Techniques for Supercomputers: Performance Issues on Modern Multicore Architectures

Resource Scalability Cache Coherence Topology and Pinning Dynamic Clock Speeds

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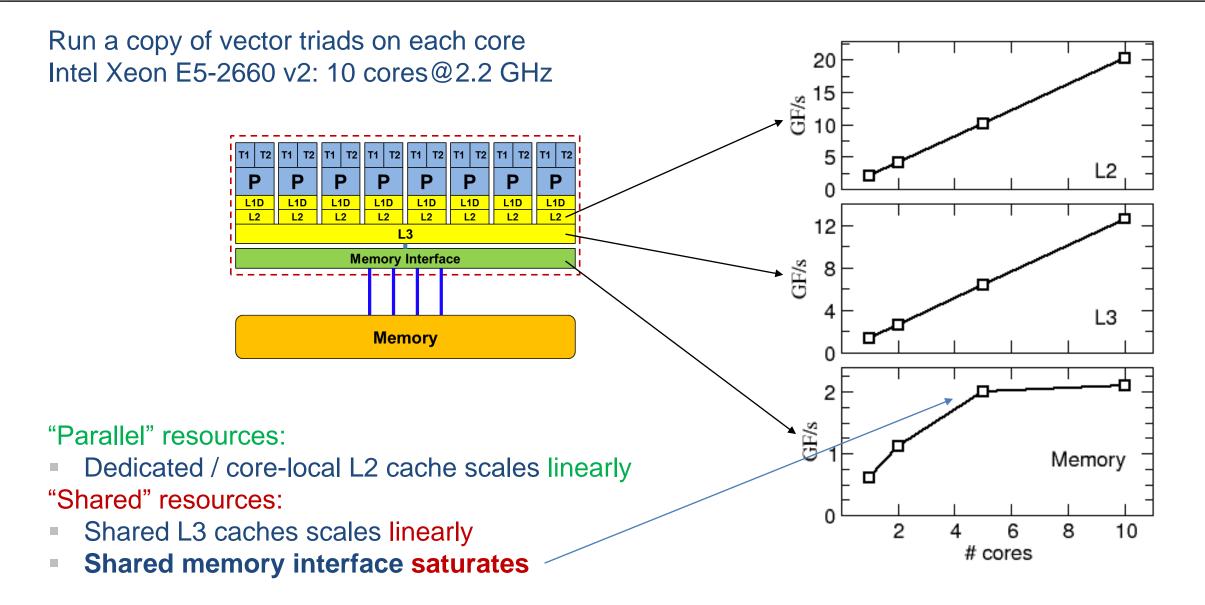




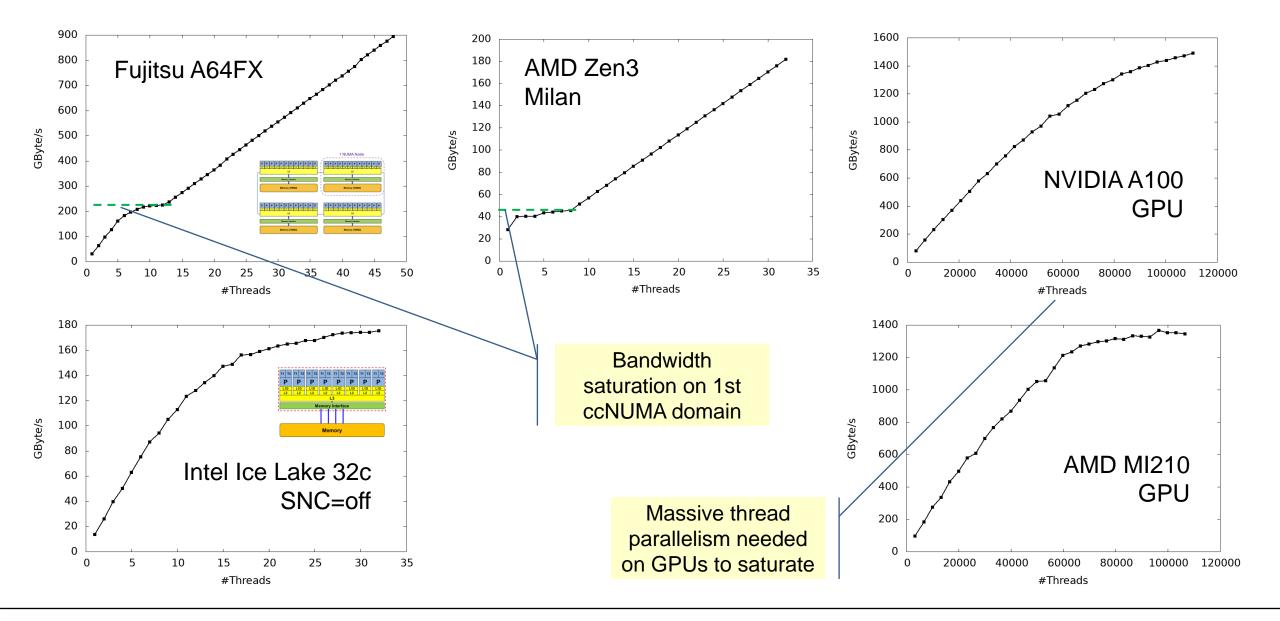


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## Scalable data paths on multicores?!

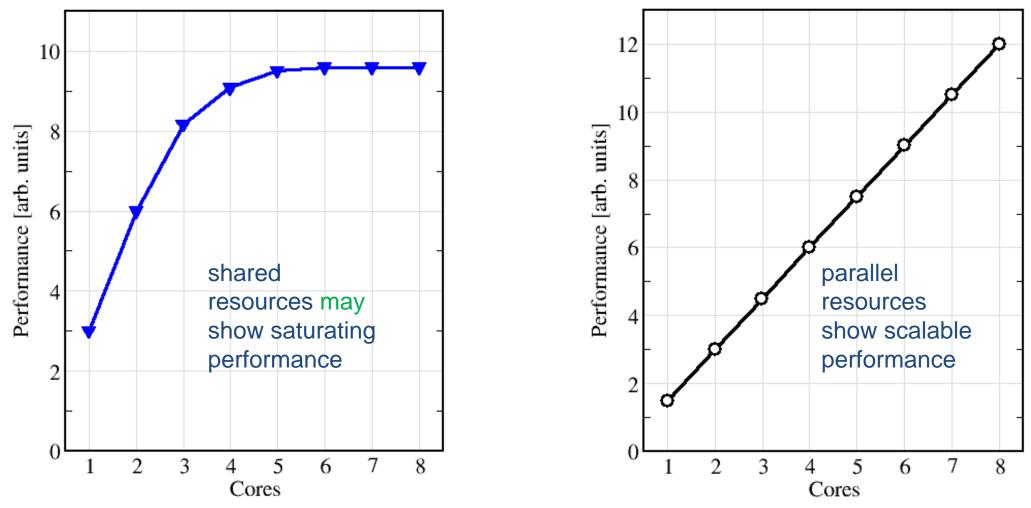


## Memory bandwidth saturation (read-only)



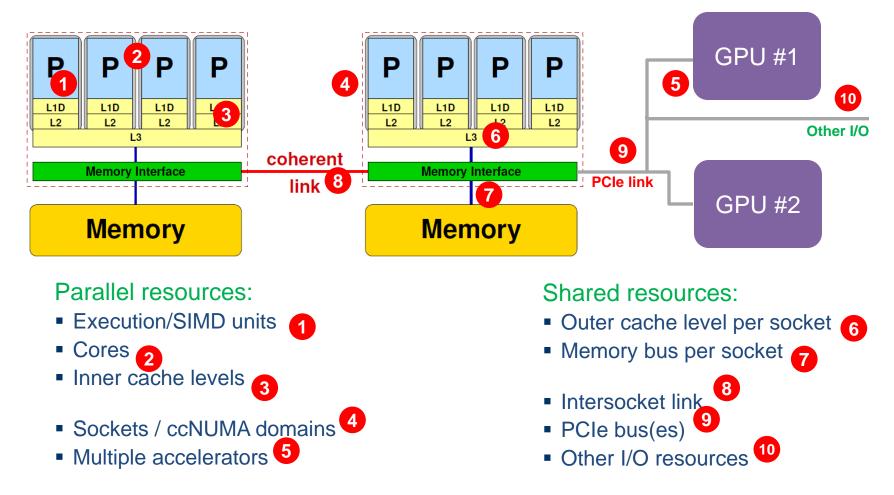
## Parallel/shared resources: Scalable/saturating behavior

 Clearly distinguish between "saturating" and "scalable" performance on the chip level



## Compute nodes: Parallel and shared resources

#### Parallel and shared resources within a shared-memory node



How does hardware scalability impact your parallel code?



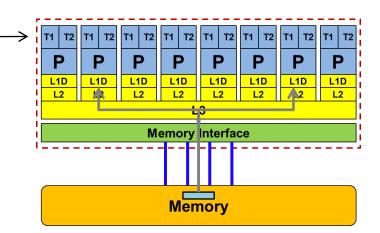


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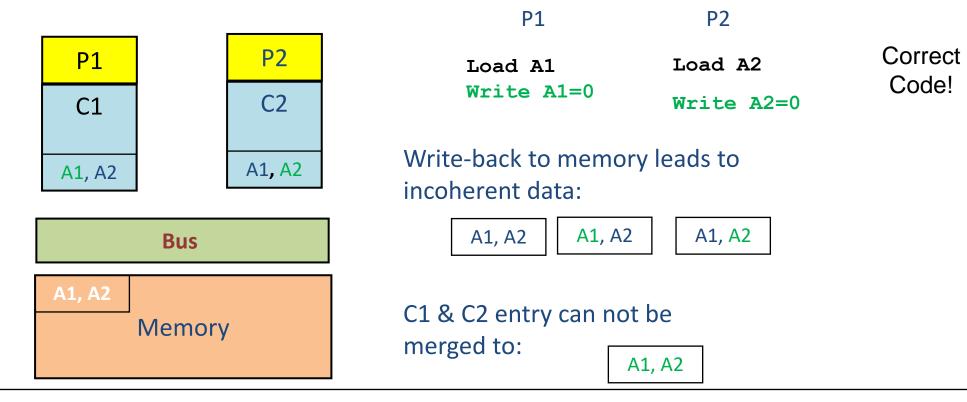
## Shared-Memory parallel computers: cache coherence

- Cache coherence in shared-memory multi-core/-processor architecture
  - Copies of same cache line may reside in different caches (Example: If 2 cores load same CL to L1 there are 5 copies in various caches)
  - If one core updates data (usually in its L1), other copies become inconsistent/outdated
  - Consistency of cache line copies is ensured by cache coherence protocols

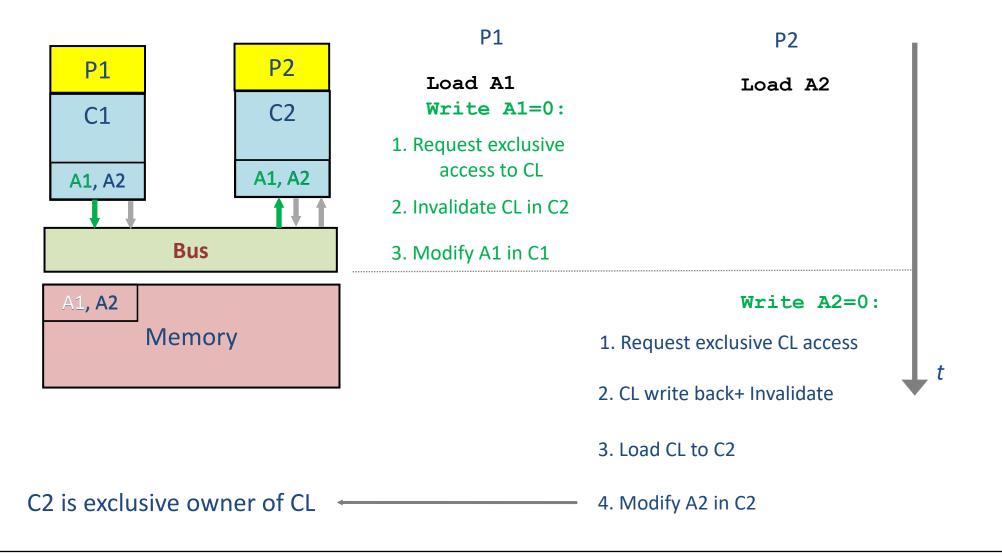
 Cache coherence protocols do not alleviate correct parallel programming for shared-memory architectures!



- Data in cache is only a copy of data in memory
  - Multiple copies of same data on multiprocessor systems
  - Cache coherence protocol/hardware ensure consistent data view
  - Without cache coherence: shared cache lines can become clobbered: (Cache line size = 2 WORD; [A1,A2] are in a single CL)



Cache coherence protocol must keep track of cache line status



- Widespread cache coherence protocol: MESI protocol
- A cache line can have four different states:
  - Modified: Cache line has been modified in this cache, and it resides in no other cache. Cache line needs to be evicted to ensure memory consistency
  - Exclusive: Cache line has been read from main memory but not (yet) modified.
    There are no (valid) copies in other caches
  - Shared: Cache line has been read from memory but not modified. There may be valid copies in other caches
  - Invalid: This cache line does not reflect any sensible data. Usually this happens if the cache line was in S state and another processor request exclusive ownership

- Cache coherence can cause substantial overhead
  - may reduce available bandwidth
- Different implementations
  - Snoop: On modifying a CL, a CPU must broadcast its address to the whole system
  - Directory, "snoop filter": Chipset ("network") keeps track of which CLs are where and filters coherence traffic
- Directory-based ccNUMA can reduce pain of additional coherence traffic

But always take care:

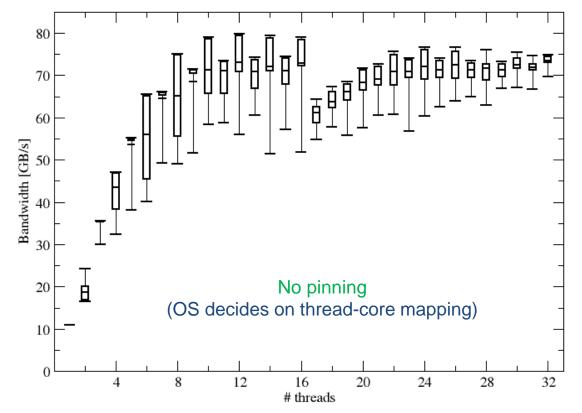
Multiple processors should never write frequently to the same cache line ("false sharing")!





Performance Issues on Modern Multicore Architectures Resource Scalability Cache Coherence Topology and Pinning Dynamic Clock Speeds

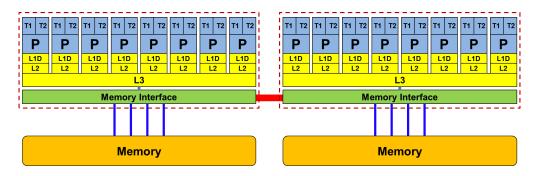
## Performance on Multicores: Anarchy vs. thread pinning



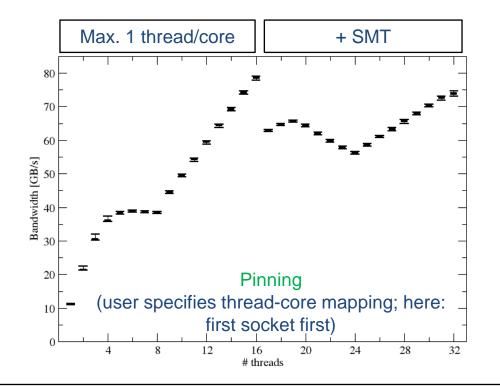
Experiment:

Run STREAM benchmark 100 times for each thread count

→ High performance variation without pinning

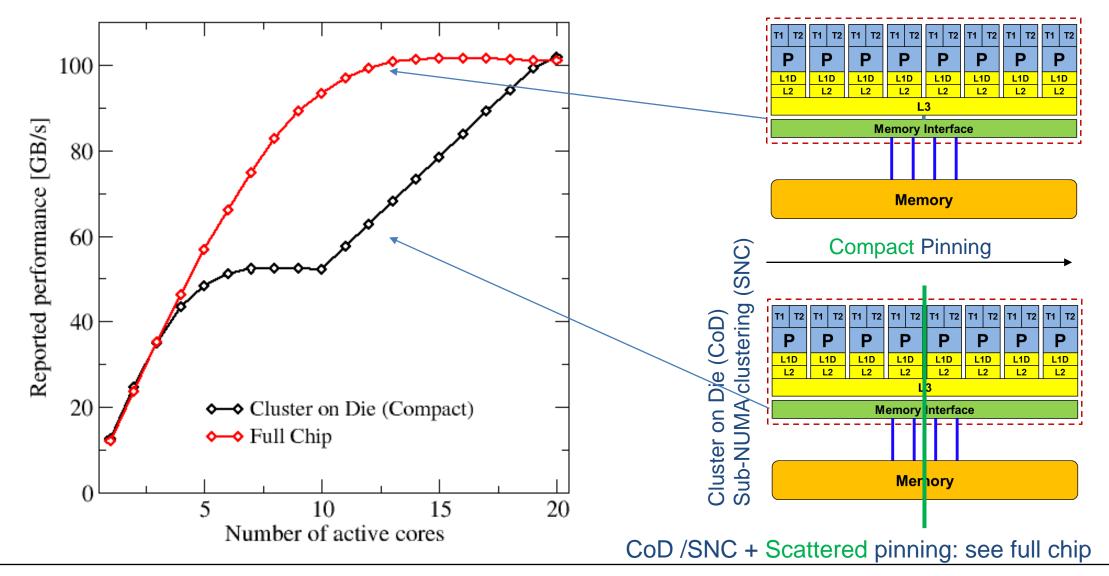


2 x 8-core processor (+SMT)



## Performance on Multicores: Scalability, CoD/SNC, Pinning

Performance scalability of STREAM triads on 20 core chip



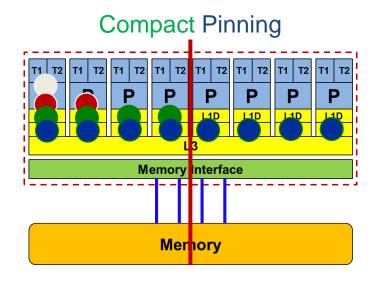
## Controlling topology / pinning

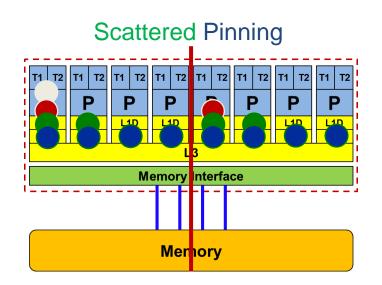
- Highly OS-dependent system calls
  - But available on all systems

Linux: sched\_setaffinity()

Windows: SetThreadAffinityMask()

- Support for "semi-automatic" pinning in some environments
  - All modern compilers with OpenMP support
  - Generic Linux: taskset, numactl, likwid-pin (see tutorial)
  - OpenMP 4.0





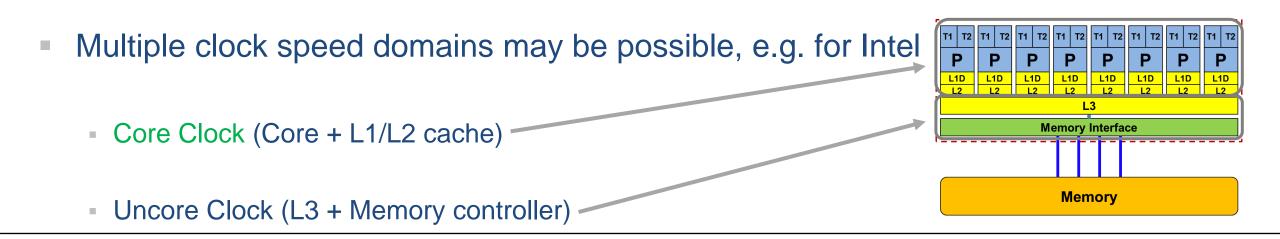




Performance Issues on Modern Multicore Architectures Resource Scalability Cache Coherence Topology and Pinning Dynamic Clock Speeds

## **Dynamic Clock Speeds: Basics**

- Modern multicore processors have a maximum power budget (TDP)
- Power consumption of given chip depends on:
  - Actual workload (#cores, SIMD Units active, clock speed,...)
  - Chip production quality or environmental conditions (e.g. temperature)
- Dark silicon: Parts of the chip run at (substantially) lower clock speed
- Turbo Mode: Processor decides dynamically on clock speed: Increasing ressource utilization / temperature → decreasing clock



**Thermal Design Power** 

## **Dynamic Clock Speeds: Frequencies**

- Frequency range for each multicore processor series (e.g. for Intel Xeon E5-2697 v4: 1.2 GHz,...,3.6 GHz)
- Two clock speed limits if using all cores of a modern multicore processor
  - CPU base frequency (a.k.a. nominal frequency): Minimum guaranteed clock speed if all cores are active (e.g. 2.3 GHz)
  - CPU all core turbo: Maximum supported clock speed if all cores are active (e.g. 2.8 GHz)
  - These clock speeds may may be different for the SIMD instruction set (SSE, AVX, AVX-512) used (e.g. 2.0 GHz / 2.7 GHz base / all core turbo for AVX code).
- Lower core counts: Clock speeds may stay within frequency range

### **Dynamic Clock Speeds: Overview**

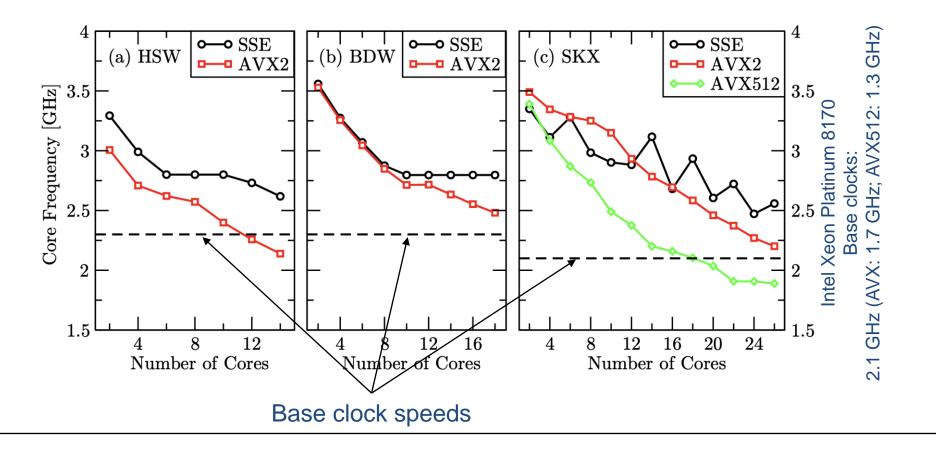
- Clock speeds when using all cores may dynamically vary by 20% 30%
- Lower clock speeds for AVX (wide) SIMD units
- Using few (one) cores may boost clock speed by up to 50%!

Microarchitecture	Sandy Bridge-EP	Ivy Bridge-EP	Haswell-EP	Broadwell-EP	Zen	Power 8
Manufacturer	Intel	Intel	Intel	Intel	AMD	IBM
Chip model	Xeon E5-2680	Xeon E5-2690 v2	Xeon E5-2695 v3	Xeon E5-2697 v4	Epyc 7451	
Release date	Q1/2012	Q3/2013	Q3/2014	Q1/2016	Q4/2017	Q2/2014
Cores/threads	8/16	10/20	14/28	18/36	24/48	10/80
Latest SIMD ext.	AVX	AVX	AVX2, FMA3	AVX2, FMA3	AVX, FMA3	VSX
CPU freq. range	1.2–3.5 GHz	1.2–3.6 GHz	1.2-3.3 GHz	1.2–3.6 GHz	1.2–3.6 GHz	2.1–3.5 GHz
Base freq.	2.7 GHz	3.0 GHz	2.3 GHz	2.3 GHz	2.3 GHz	2.9 GHz
AVX base freq.		—	1.9 GHz	2.0 GHz		
All core turbo	3.1 GHz	3.3 GHz	2.8 GHz	2.8 GHz	3.2 GHz	3.5 GHz
AVX all core turbo			2.6 GHz	2.7 GHz		_
Uncore freq. range			1.2-3.0 GHz	1.2–2.8 GHz		

J. Hofmann, " A First-Principles Approach to Performance, Power, and Energy Models for Contemporary Multi- and Many-Core Processors", Dissertation, FAU, 2019

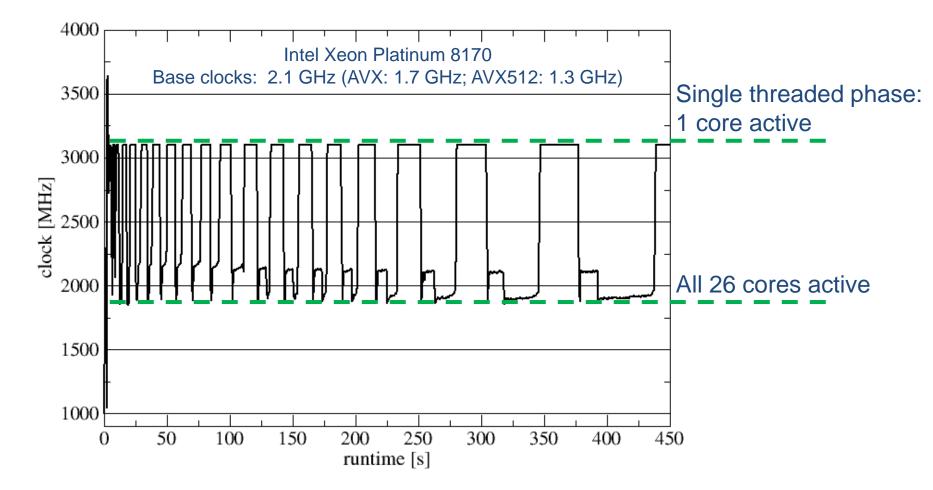
## Dynamic Clock Speeds: Impact of cores / SIMD

- Running LINPACK on one chip (Intel mkl implementation)
- Processor adapts clock speeds dynamically to ressource utilization (cores, SIMD widths)
- Base clock speeds are lower bounds



## Dynamic Clock Speed: Dynamic Adaption

#### Running multithreaded LINPACK (Intel mkl version; AVX512) on one Intel Skylake Monitoring clock speeds over time

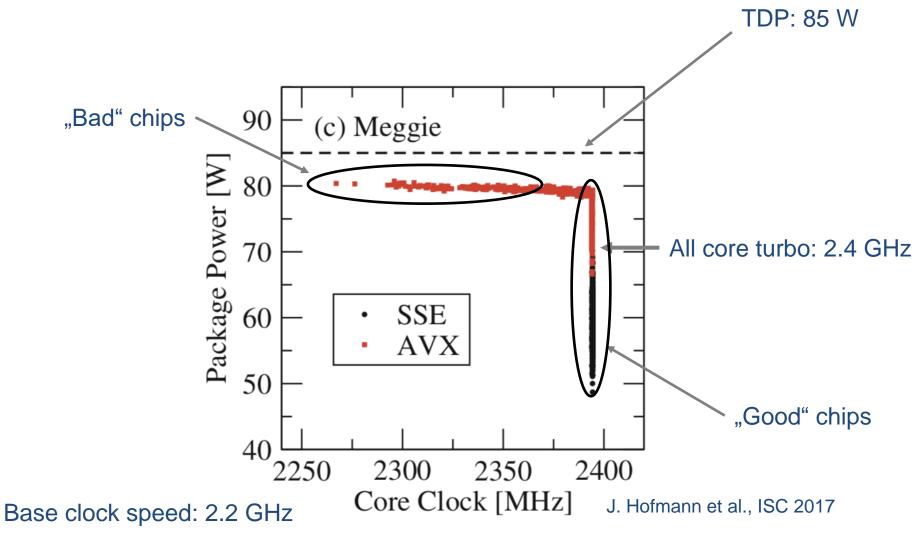


At execution time the processor dynamically overclocks to always give you the full TDP envelope!

PTfS 2025

### Dynamic Clock Speed: Chip Quality

LINPACK: Power consumption vs. dynamic clock speed (1456 Intel Xeon E5-2630v4 chips)



## Dynamic Clock Speeds: Summary

- Turbo Mode may speed up your application execution
- Turbo Mode may introduce (strong) performance fluctuations: Chip quality, environment temperature,...
- Performance measurements should be done with fixed clock speed (e.g. using likwid) to CPU base frequency (default in PTfS)
- Information about clock speeds:
  - likwid-setFrequencies
  - https://en.wikichip.org/wiki/WikiChip
  - https://ark.intel.com/content/www/de/de/ark.html#@Processors

#### Lecture plan until July

- 3.6.2024: Lecture (Topologies & Clock Speeds)
- 4.6.2024: Lecture (OpenMP)
- 5.6.2024: Lecture (OpenMP)
- 10.6.2024: No Lecture
- 11.6.2024: Lecture (GPU Sebastian Kuckuk)
- 12.6.2024: Lecture (GPU Sebastian Kuckuk)
- 17.6.2024: Lecture (Roofline)
- 18.6.2024: Lecture (Roofline)
- 19.6.2024: No Lecture
- 24.6.2024: Lecture (Roofline Case Studies)
- 25.6.2024: Lecture (Roofline Case Studies)
- 26.6.2024: No Lecture